

An Alternative Approach to Inflation in
String Theory

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Autumn workshop on String/M-theory

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Reference List:

Klebanov and Strassler, hep-th/0007181

Giddings, Kachru & Polchinski, hep-th/0105097

Dewolfe & Giddings, hep-th/0208123

Kachru et al (KKLT), hep-th/0301240

Quevedo, (better review paper), hep-th/0210292

Kachru, et al, (KKLMMT), hep-th/0308055

Wang & Xiao, hep-th/0410175

Lu & Wang, in preprint

Outline:

I. Introduction

- Some ideas in String/brane inflation
- $D3 - \bar{D}3$ inflation
- Difficulties
- Our new idea.

II. Dynamics of $\bar{D}3$ -branes in Compactified KS geometry

- World volume action
- Inflaton, effective potential

III. Incorporate inflation

- Various constraint from inflation: slow-roll, Number of e -folding, density perturbative, ...

- Grace exit
- Modulus stabilization

IV. Summary & Discussions

I. Introduction

A. Inflation in String/brane models:

— old ideas:

$10-d \xrightarrow{\text{compactification}} 4-d \rightarrow V_{\text{eff}}(\phi_i)$

ϕ_i : Various moduli from string compactification

→ inflation?

Difficulties: ① It is hard to obtain a flat potential

② $2n$ general end with a SUSYic Minkowski or AdS vacuum

— Brane inflation: * Adding probe brane moving in background $R^{1,3} \times M_6$, with ~~the~~ fixing of all of background moduli, and M_6 compactified.

* The positions of brane behave as inflation.

— Brane world inflation: The transverse space need not to be compactified. Hard to obtain this type of models from string theory.

B. D3 - D3 Inflation.

- Basic idea: There is attractive force between D3 & D3.

⇒ The distance between them decrease

⇒ New modulus, acts as inflation.

- Flat background, with toroidal compactification

$$V(r) = 2T_3 \left(1 - \frac{1}{2\pi^2} \frac{T_3 K_0^2}{r^4} \right) \quad T_3 = \frac{1}{(2\pi\alpha')^3 g_s l_s^3}$$

$$\rightarrow V(\phi) = 2T_3 \left(1 - \frac{T_3^2 K_0^2}{2\pi^2 \phi^4} \right)$$

* Slow-roll parameters:

$$\epsilon = \frac{M_{Pl}^2}{2} \left(\frac{V'}{V} \right)^2 \quad \eta = M_{Pl}^2 \frac{V''}{V}$$

$$M_{Pl}^2 = \frac{1}{8\pi G} \Rightarrow \eta = -\frac{10}{\pi^2} \left(\frac{1}{r} \right)' \sim -0.3 \left(\frac{1}{r} \right)' \quad L \gg r$$

→ Does not yield slow-roll!

- In warped, BPS, with 5-form flux background:

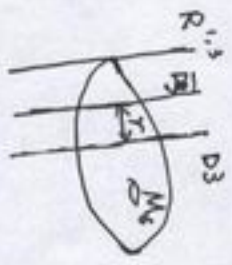
$$ds^2 = e^{2A(r)} dx_\mu dx^\mu + e^{-2A(r)} dy_m dy^m \quad r^2 = \gamma_m \gamma^m$$

$$G_{(4)} \sim e^{4A(r)}$$

$$V_{\text{eff}} = V_0 + V_{D3} + V_{\overline{D3}} + V_{\text{int}}$$

locate at r_1

locate at r_0



V_0 :: Background Vacuum energy after Compactification.

V_{D3} : Energy from tension } \rightarrow Cancelled by no-force condition
Energy from $F_{(2)}$ }

V_{D3} : Energy from tension } $\rightarrow 2T_3 e^{4A(r_0)}$
Energy from $F_{(2)}$ }

V_{int} : Interaction between $D3$ & $\bar{D3}$, Computed as follows:

① Adding $D3$ into background, change background to:
 $e^{-4A(r_0)} \rightarrow e^{-4A(r_1)} + \frac{1}{N} e^{-2A(r_1, r_0)}$ w/ r_1 - position of $D3$

② The change of $\bar{D3}$ potential in new background:

$$S e^{4A(r_0)} = 2 - \frac{1}{N} 2T_3 e^{8A(r_0) - 4A(r_0, r_1)} \quad \text{w/ } r_0 - \text{position of } \bar{D3}$$

$$\Rightarrow V_{eff} = V_0 + 2T_3 e^{4A(r_0)} \left(1 - \frac{1}{N} e^{4A(r_0) - 4A(r_0, r_1)}\right)$$

Assuming : $V_0 = 0, \quad r_0 = \text{const.} \quad r_1 \rightarrow \text{dynamical variable}$

$$\Rightarrow \eta = \frac{1}{N k_0 T_3} (\Delta A'' - (\Delta A')^2) e^{4A(r_0) - 4A(r_0, r_1)}$$

* η may be small for N large, $e^{4A - \Delta A}$ small

Example 1: $AdS_5 \times X_5 : e^{-4A} = \frac{R^9}{r^2}, e^{-4A(r, r_0)} = \frac{R^9}{r_1^2}$

$$\eta = \frac{L^6}{N k \alpha^2 T^3} \frac{2 \alpha r_0^4}{r_1^6} \ll 1 \quad \text{for } r_1 \gg r_0$$

Example 2: Embedding Klebanov - Strassler Geometry in

F-theory Compactification: $e^{4A_0} \sim e^{-\frac{8\pi k}{3g_{SM}}}$

After moduli stabilization: $-k = \frac{1}{4\alpha^2} \int_5 H_{(5)}$

$$M = \frac{1}{4\alpha^2} \int_4 F_{(4)} \quad -k = \frac{1}{4\alpha^2} \int_5 H_{(5)}$$

can achieve a small η :

C): Incorporate with moduli stabilization

String Compactification:

$$ds^2 = e^{-6u(x)} g_{uv} dx^u dx^v + e^{2u(x)} (\tilde{g}_{mn}(y) + T^I(x) g_{2imn}(y)) dy^m dy^n$$

$$(p = \alpha + i e^{\alpha u})$$

$I_{imp} = e^{4u} \rightarrow$ volume modulus
 $T^I \rightarrow$ remaining Kähler & complex structure moduli

$$V_4 \sim e^{-12u} V_{eff} \sim V_{eff} / (I_{imp})^3 \sim V_{eff} / L^{12}$$

- Assume ρ -modulus is stabilized by $N=1$, SUGRA potential:

$$V = e^K (g^{i\bar{j}} D_i W D_{\bar{j}} \bar{W} - 3|W|^2)$$

w/ no-scale type Kähler potential, $K = -3 \ln(-i(\rho - \bar{\rho}))$

R Non-perturbative superpotential, $W = W(\rho)$

- Insertion of D_3/\bar{D}_3 usually change Kähler structure:

$$K = -3 \ln(\rho \bar{\rho}), \quad 2\tau = -i(\rho - \bar{\rho}) + T(\phi, \bar{\phi})$$

w/ $\phi, \bar{\phi}$ - position of D_3/\bar{D}_3 , inflation,

as well as $N=1$ potential:

$$V = e^K (g^{i\bar{j}} D_i W D_{\bar{j}} \bar{W} - 3|W|^2) + \frac{D}{r^2} \rightarrow \text{from } \bar{D}_3$$

$$\Rightarrow V = \frac{1}{6r} \left\{ |W'|^2 \left(1 + \frac{1}{2r} \frac{T_{i\bar{j}} T_{i\bar{j}}}{T_{\phi, \bar{\phi}}} \right) - \frac{3}{2r} (W W' + c.c.) \right\} + \frac{D}{r^2}$$

w/ $W' = \partial_\rho W$

Usually D_3/\bar{D}_3 are put along radial direction of

transverse space:

$$T(\phi, \bar{\phi}) = \sum_n c_n (\phi \bar{\phi})^n$$

$c_1 = \bar{\sigma}^T \sigma M_{\bar{p}}^2$ determined by kinetic term of ϕ :

$$M_{\bar{p}}^2 K_{\phi\bar{\phi}} \partial_\mu \phi \partial^\mu \bar{\phi} \rightarrow \frac{3T_3}{24m_p^2} \partial_\mu \phi \partial^\mu \bar{\phi}$$

⇒ Normalized variable (inflation): $\varphi = \sqrt{\frac{3T_s}{2M_p^2}} \phi$

w/: $\rho_e = \text{const.}$ — Stabilized modulus

$$\Rightarrow V = \left\{ \frac{W(\rho_e)^2}{6 M_p^2 \rho_e} - \frac{1}{4(M_p \rho_e)^2} (W(\rho_e) W'(\rho_e) + c.c.) \right\} + \frac{D}{(2M_p \rho_e)^2} \left(1 + \frac{2}{3M_p^2} \varphi \bar{\varphi} \right)$$

$$\Rightarrow \eta = \frac{2}{3}$$

Conclusion: $D3 - \bar{D3}$ inflation is not consistent with (volume) modulus stabilization!

D): Our new idea:

$D3/\bar{D3}$ - branes in background with 3-form flux:

→ Expand into D5 with topology $R^3 \times S^2$

— Radius of S^2 as inflation!

Background with flux?

Various constraints from inflation?

Compactification R^6 modulus stabilization?

II. Dynamics of $\overline{D3}$ -branes in Compactified KS geometry

— Motivations

* Why Klebanov - Strassler geometry?

Δ present R-R 3-form flux

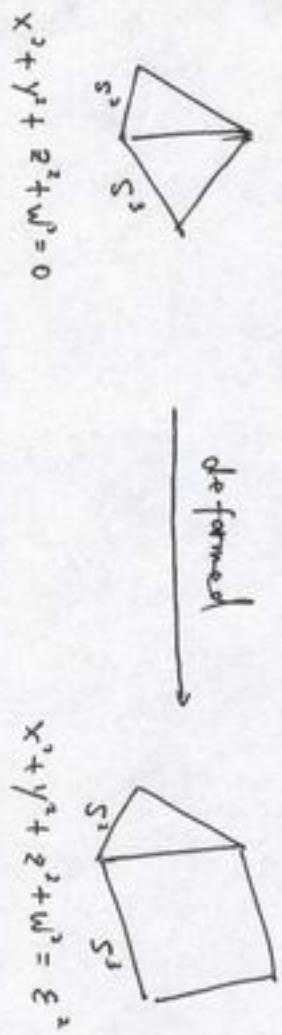
Δ Consistent with F-theory Compactification

* Why $\overline{D3}$ -branes?

Extra Energy from tension of $\overline{D3}$ R flux
 \Rightarrow ADS phase $\xrightarrow{\text{uplift}}$ ds phase

— The Klebanov - Strassler geometry

* Deformed conifold:



* KS geometry: IIB SUGRA solution

+ N D3
 + M D5 } \rightarrow Apex of deformed conifold

$$g_{S_{10}^2} = h^{-1/2}(\tau) \eta_{\mu\nu} dx^\mu dx^\nu + h^{1/2}(\tau) ds_5^2$$

$F_{(1)}, H_{(3)} \neq 0, \quad \Phi = \text{const.}$

\rightarrow dissolve into fluxes



— Embedding K S geometry into F-theory Compactification

* Calabi-Yau 3-fold geometry and smoothly glue with a compactified manifold M_6

* Tadpole cancellation condition:

$$\frac{\chi(X)}{24} = N_{D3} - N_{\bar{D3}} + \frac{1}{24} \int_{M_6} H_{(3)} \wedge F_{(3)}$$

* Dirac Quantization

$$\frac{1}{4\pi^2} \int_A F_{(2)} = M \qquad \frac{1}{4\pi^2} \int_B H_{(3)} = -K$$

— Adding $\bar{D}3$ -branes

* Assuming K S geometry has been embedded into F-theory Compactification, without extra insertion of $D3/\bar{D}3$ branes,

• Tadpole condition: $\frac{\chi(X)}{24} = MK$

~~* New introduction of p $\bar{D}3$~~

• We end with an AdS vacuum.

* Now introducing p $\bar{D}3$ -branes into background while the topology of CY 4-fold, X , is not changed. The tadpole condition can be satisfied by turning on more flux:

$$\frac{\chi(X)}{24} = -N_{\bar{D3}} + (M+S)K = MK$$

$$\Rightarrow p = N_{\bar{D3}} = SK, \quad S \in \mathbb{Z}$$



* The background D3 charge $N = M K$. \Rightarrow

The backreaction of $\bar{D}3$ can be ignored when $S \ll M$

* The energy from T_3 & extra flux: \rightarrow ~~AdS~~ \rightarrow dS

— World-volume action:

* $S = S_{D3} + S_{CS}$

$$S_{D3} = -T_p \int d^{p+1}x \cdot \text{STr} \left\{ e^{-\tau} \left(-\det(P[E_{ab} + E_{ai}(\Omega^{-1} - S)^{ij} E_{jb}] + 2\pi \ell_s^2 F_{ab}) \right)^{\frac{p}{2}} \sqrt{\det(\Omega^i_j)} \right\}$$

$$S_{CS} = M_p \int \text{STr} \left(P \left[e^{2\pi i \ell_s^2 F_{ab}} \left(\frac{1}{2} C^{(n)} e^{\theta} \right) \right] e^{2\pi \ell_s^2 F} \right)$$

$$E_{ab} = B_{ab} + G_{ab}, \quad T_p = \frac{M_p}{g_s} = \frac{1}{g_s (2\pi)^p \ell_s^{p+1}}$$

$$\Omega^i_j = \delta^i_j + 2\pi i \ell_s^2 [\Phi^i, \Phi^j] E_{ij}$$

$$i+1 \dots n \quad C^{(n)} = \frac{1}{(n-2)!} \bar{\Phi}^{i_1} \bar{\Phi}^{i_2} \dots \bar{\Phi}^{i_n} dx^{i_1} \wedge \dots \wedge dx^{i_n}$$

* We choose the S^1 of deformed manifold as our solution ansatz. It ~~is~~ is embedded into a local flat 3-d

Space near apex:

$$dt^2 + r^2 d\Omega_i^2 = dy_1^2 + dy_2^2 + dy_3^2$$

$$* F_{(3)} \rightarrow \frac{\sqrt{3} \epsilon^{ijk}}{g_s M \ell_s^2} dx_i \wedge dx_j \wedge dx_k \wedge dt \wedge dy_1 \wedge dy_2 \wedge dy_3$$

$$H_{(3)} \rightarrow \sqrt{3} g_s M \ell_s^2 dx_1 \wedge dx_2 \wedge dx_3 \Leftrightarrow B_{(3)} = \frac{g_s M \ell_s^2}{2\sqrt{3}} \epsilon^{ijk} y_i dy_j \wedge dy_k$$

* Static gauge: $z_a = x_a, \quad y_i = 2\pi \ell_s \bar{\Phi}_i \quad i=1, 2, 3$

* Effective potential

Ansatz for solution of EOM: $\Phi_i = \frac{m_i}{f} u^{J_i}$, $[J_i, J_j] = i \epsilon_{ijk} J^k$

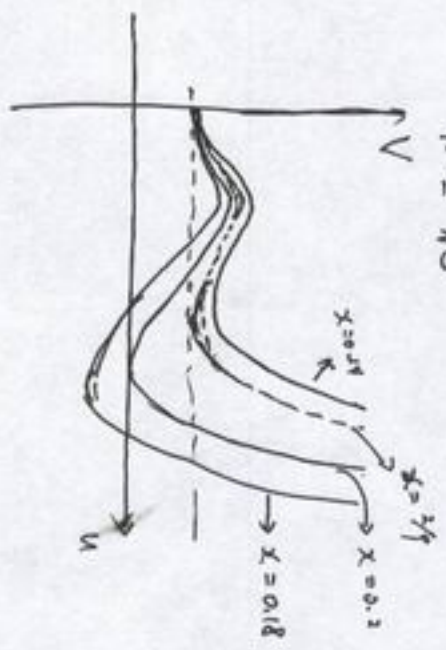
$\Rightarrow V(u) = V_0 + \frac{p(p-1)m^2}{4f^2} \left(\frac{1}{2} u^2 - \frac{1}{3} u^3 + \frac{\lambda}{4} u^4 \right)$

w/:

$$V_0 = \frac{p T_5 \epsilon^2 g_s}{g_0 g_i M^2 g_s^4}, \quad m^2 = \frac{2 a_1 \epsilon^2 g_s}{g_0^2 g_i M^2 g_s^4}, \quad f = \frac{\sqrt{6} \pi \epsilon^2 g_s}{2 a_0 \sqrt{g_s} M^2}$$

$$\chi = \frac{2 \pi g_s (1-\lambda) m^2}{f^2} = \frac{8 a_1}{3} (1-\lambda), \quad \lambda = \frac{K^2 p^2 - 1}{g_s^2 M^2}$$

$$a_0 \approx 0.718, \quad a_1 = 3^{-4/3}, \quad K^2 \approx \sqrt{3}$$



* Static solution:

$$u = u_0^{(2)} = \frac{1}{2\lambda} (1 \pm \sqrt{1-4\lambda})$$

$$V_{max} = V_0 - \frac{p(p^2-1)m^2}{8\lambda^3 f^2} [1-6\lambda + 6\lambda^2 - (1-4\lambda)^{3/2}] \geq V_0 \quad \text{for } \lambda \in [0, \frac{1}{4}]$$

$$V_{min} = \dots \leq V_0 \quad \text{for } \lambda \in [0, \frac{3}{8}]$$

• Vacuum at $\alpha = 0$ ($V = V_0$) \rightarrow D3 Configuration.

• Vacuum at $u = u_0^{(1)}$ ($V = V_{min}$) \rightarrow D5 Configuration

$R^3 \times S^2$

III. Incorporate with Inflation

- * Shift potential by defining: $U = V + U_0$

~~$$V = V_{max} \int \frac{1}{4x} (\sqrt{1-4x} - 1 + 4x) dx$$~~

$$V = V_{max} + \frac{p(p-1)m^6}{4f^2} \left\{ -\frac{1}{4x} (\sqrt{1-4x} - 1 + 4x) v^2 + \frac{1}{6} (1-3\sqrt{1-4x}) v^3 + \frac{x}{4} v^4 \right\}$$

- * Inflation: $\varphi_i = \frac{m^2}{f_0} v J_i$

Because we find a homogeneous solution, we can use one field to replace its effect:

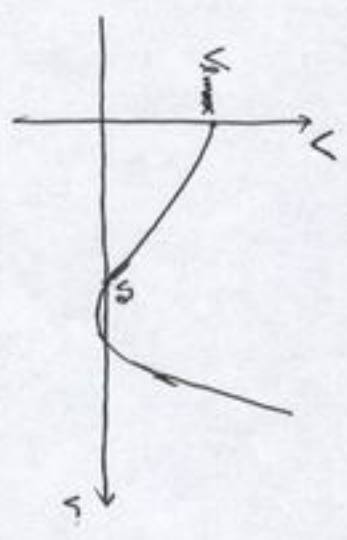
~~$$\phi = \frac{2m^2}{f_{max}} v \sqrt{p(p-1)}$$~~

- * Grace exit of inflation:

- o The total energy of system is lowered with decrease of x , and can be even negative!
- o The negative energy is unphysical! There is a critical point $\varphi_{v=v_c} \Rightarrow V(U_c) = 0$.
- o The spherical D5-brane at $v=v_c$ annihilates one unit R-R 3-form flux, and dissolves into $(K-p)$ D3-branes;

$$\frac{N}{24} = MK - p = (M-1)K + (K-p)$$

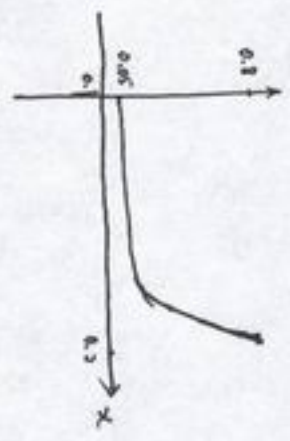
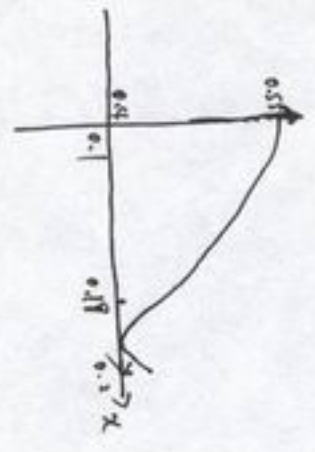
o Because critical point is presented only for $x \leq 0.198735$,
 we require $x \leq 0.1987$ in order inflation can ~~occur~~ ^{end!}



* define $S_1(x) = -\frac{2x(1-3\sqrt{1-4x})U_0(x)}{3(\sqrt{1-4x}-1+4x)}$

$$S_2(x) = \frac{x^2 U_0^2(x)}{\sqrt{1-4x} - 1 + 4x}$$

The curves of S_1 & S_2 are as follows:-



In other words, if we expect the inflation occurs between $v=0$ and $v=v_0$, we can ignore v^3 and v^4 terms in potential.

$$\Rightarrow V = \frac{\rho m^6}{4f^2 k^2} \left\{ \frac{3a_0^3 k^2}{32\pi^2 a_1^3} - \frac{1}{4x} \left(1 - \frac{3x}{8a_1}\right) (\sqrt{1-4x} - 1 + 4x) v^2 \right\} + O(v^3)$$

* Various Constraints from inflation:

$$\epsilon = \frac{\bar{M}_p^2}{2} \left(\frac{V'}{V}\right)^2 \ll 1$$

$$\bar{M}_p^2 = \frac{2L^6}{(2\pi)^3 \alpha_s^2 g_s^2}$$

L - scale of compact space

$$\eta = \bar{M}_p^2 \frac{V''}{V} \ll 1$$

$$N_e = -\frac{1}{M_p^2} \int_{\phi_i}^{\phi_f} \frac{V}{V'} d\phi \sim 60$$

$$\delta_H \approx \frac{1}{M_p^3} \frac{V''}{V'} \sim 10^{-5}$$

$\therefore V(u)$ decrease with increase of v

v $|V'|$ increase

v V'' is nearly constant

\Rightarrow The maximum of δ_H is at $v = V_{pi}$

• The maximum of ϵ is at $v = V_f$

\Rightarrow • The condition for δ_H tells us where the inflation starts

• The condition for ϵ tells

• The condition for η & N_e gives constraints on background!

$$* \quad \epsilon = \frac{\bar{M}_p^2}{2} \left(\frac{V'}{V} \right)^2 \ll 1$$

The inflation end at $\epsilon \sim 1$, i.e.,

$$\frac{\bar{M}_p^2}{2} \cdot \frac{f^2}{4m^2 p (p^2 - U)} \left(\frac{u(x) V_f}{A - \frac{1}{2} u(x) V_f^2} \right)^2 < 1$$

$$\Rightarrow v_i: \quad u(x) = \frac{1}{2x} \left(1 - \frac{3x}{8a_1} \right) (\sqrt{1-4x} - 1 + 4x)$$

$$A = \frac{3a_0^2 K^2}{32\pi^2 a_1^2} \approx 0.5$$

$$Y^2 = \frac{f^2 \bar{M}_p^2}{8m^2 p (p^2 - U)} = \frac{3\pi a_0^2 K^2}{32 a_1^2} \cdot \frac{g_s \rho_s^4 \bar{M}_p^2}{p \epsilon^{4/3}} \left(1 - \frac{3x}{8a_1} \right)^{-1}$$

$$\approx \frac{5 \cdot 10^{15} g_s \rho_s^4 \bar{M}_p^2}{p \epsilon^{4/3}} \left(1 - \frac{3x}{8a_1} \right)^{-1}$$

$$\Rightarrow \quad V_f < -y + \sqrt{y^2 + \frac{2A}{M^2}}$$

$$* \quad \delta H \sim 10^{-5}$$

In order to obtain enough e-folding, the v_i must be sufficiently small, Then

$$\delta H \approx \frac{\sqrt{p} m^2}{\sqrt{8} K f \bar{M}_p} - \frac{A^{3/2}}{y M v_i} \sim 10^{-5}$$

$$\Rightarrow \quad v_i \sim \frac{10^5 \sqrt{p} m^2}{\sqrt{8} K f \bar{M}_p} \frac{A^{3/2}}{y M}$$

$$\approx \frac{6 \times 10^5 \cdot \frac{\xi^2}{g_s \rho_s^6 \bar{M}_p^3 M}}{\left(1 - \frac{3x}{8a_1} \right)^{3/2}}$$

$$\approx \frac{6 \times 10^5 \cdot \frac{g_s}{\rho_s^6 \bar{M}_p^3 M}}{\left(1 - \frac{3x}{8a_1} \right)^{3/2}}$$

$$* N_e = -\frac{1}{M_p^3} \int_{t_i}^{t_f} \dot{V} \, dt$$

$$= \frac{1}{2y^2} \left\{ \frac{A}{M} \ln \frac{V_f}{V_i} - \frac{1}{4} \mu V_f^2 \right\} \sim 60$$

This happens only for $Y \ll 1$

$$\Rightarrow N_e \simeq \frac{1}{2y^2} \left\{ \frac{A}{2M} \ln (2AM \rho^3/g_s) + \frac{3A}{4M} \ln Y - \frac{A}{2} - 6.4 \right\} \sim 60$$

To find minimal ρ^3/g_s , we have:

$$Y^2 = \frac{A}{80M}$$

$$\Rightarrow 2AM \rho^3/g_s = \frac{(80M)^3}{A^3} \text{ @ } 3+26.5M$$

$$\Rightarrow \left\{ \begin{array}{l} Y^2 \simeq 0.012 \\ \rho^3/g_s \sim 10^{12} \end{array} \right.$$

for $\mu \sim 0.1P - 0.2$

$$\Rightarrow \frac{g_s}{P} \cdot \frac{g_s^A M_p^2}{\epsilon^{4/3}} \simeq 2 \times 10^{-3}$$

$$* \eta = \bar{M}_p^2 \frac{V''}{V} \leq 4\mu Y^2/A \simeq 0.045 \ll 1$$

* More Constraints.

• we require radius of fuzzy S^2 must be smaller than L :

$$\frac{\pi R_s p}{\sqrt{8cM}} < L$$

$$\Rightarrow \frac{p^6}{512 \pi^2 R_s^2 g_s^3 M^3} < \bar{M}_P^2$$

$$\Rightarrow \frac{p^5 R_s^2}{512 \pi^2 g_s^2 M^2 \epsilon^{4/3}} < 2 \times 10^{-3}$$

• $M_{KK} \sim \frac{\epsilon^{3/4}}{g_s M R_s^2} \sim \frac{10^9}{R_s}$

• Combination: $\frac{p^5}{512 \pi^2 g_s^4 M^5} < 2 \times 10^{-20-3}$

$$\Rightarrow g_s < 10^{a+20}$$

$$\Rightarrow p^3 < 10^{16+20a}$$

~~$$g_s < 10^{-1}$$~~

~~$$M_{KK} > 10^3 \text{ GeV}$$~~

$$\Rightarrow -16 < a < -30$$

~~$$\frac{1}{R_s} < 10^{16} \text{ GeV}$$~~

$$p^2 \gg 1 \Rightarrow -7 < a < -3$$

* Modulus stabilization:

Everything like D3-D $\bar{3}$ system, except that we are dealing with a non-Abelian system. Then:

$$T(\phi, \bar{\phi}) = -\frac{p-1}{4} T_3 M_p^2 \phi \bar{\phi} + \dots$$

\Rightarrow kinetic term:

$$M_p^2 K_{\phi\bar{\phi}} T_r(\partial_\mu \phi \partial^\mu \bar{\phi}) = \frac{3(p-1) T_3}{8 M_p^2 g} \partial_\mu \phi \partial^\mu \bar{\phi}$$

\Rightarrow inflaton:
$$\varphi = \sqrt{\frac{3(p-1) T_3}{8 M_p^2 c}} \phi$$

$\Rightarrow V \propto \left(1 + \frac{2}{3p} M_p^2 \varphi \bar{\varphi}\right)$

$\Rightarrow \eta = \frac{2}{3p}$

key point: η is suppressed by $1/p$ comparing with D3-D $\bar{3}$ inflation!

* End of ~~de~~ inflation, dS vacuum R c.c.

- Add one unit extra R-R flux and $K \bar{D}3$

→ D5 with $R^3 \times S^2$

→ D5 annihilates with one unit R-R flux

→ End with AdS vacuum.

- Add ~~two~~ unit extra R-R fluxes and $2K \bar{D}3$

→ D5

→ D5 annihilates one unit R-R flux

→ Remain one unit extra R-R flux and $K \bar{D}3$

The dis appear of D5 requires:

$$\frac{(2K)^2}{g_s^2 M^2} = \frac{1}{k^2} \left(1 - \frac{3\alpha' x_1}{8\alpha_1}\right), \quad x_1 < 0.2$$

If residual $K \bar{D}3$ form a spherical D5, we require

$$\frac{K^2}{g_s^2 M^2} = \frac{1}{k^2} \left(1 - \frac{3\alpha' x_2}{8\alpha_1}\right), \quad x_2 < 2/9$$

⇒ $\alpha x_2 - x_1 = 8\alpha_1 \approx 1.85$, it is impossible! ⇒ $K \bar{D}3$ is stable

⇒ we can end with a dS vacuum with small c.c.

Summary:

- * We propose a new approach on D-brane inflation.
 - $\overline{D3}$ -branes in KS geometry
 - Myers' effect.
 - R Radius of fuzzy S^1 as inflaton
- * It satisfies all constraints from inflation.
 - ~~isotropic~~ slow-roll, Grace exit.
 - Number of e -foldings
 - scalar perturbation,
 - need large number of flux unless g_s very small.
- * Consistent with (Volume) modulus stabilization
- * Theoretical constraint S:
 - $g_s \ll 1$
 - $p^5/g_s \sim 10^{13}$
 - $p \sim g_s M$